

Tutorial: stochastic models of biochemical reaction systems

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April 17th, 2014

Goals of this tutorial

Introduce mathematical models from molecular biology – reaction networks:

- ▶ **Stochastic models** – continuous time Markov chains with stochastic mass action kinetics.
- ▶ **Deterministic models** – ODEs with deterministic mass action kinetics.

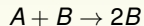
Introduce the field of **chemical reaction network theory** – 50%

Focus on **deficiency** of networks and **deficiency zero** results – 50%

Tomorrow will focus on results related to deficiency one models.

Reaction networks

Models usually begin with something called a [reaction network](#).



or



The network is a static object. We are not yet choosing a dynamics.

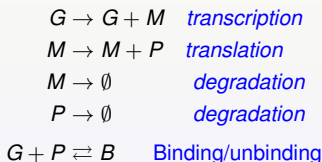
Reaction networks

- Biochemical/population networks can range from simple to very complex.

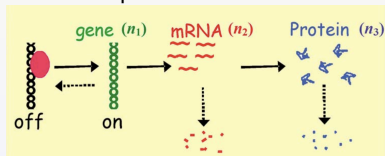
Example 1: $\emptyset \rightleftharpoons A$.

Example 2: $A + B \rightarrow 2B$
 $B \rightarrow A$

Example 3: Gene transcription & translation:



Cartoon representation:



1

Reaction networks

Example 4: EnvZ/OmpR signaling system

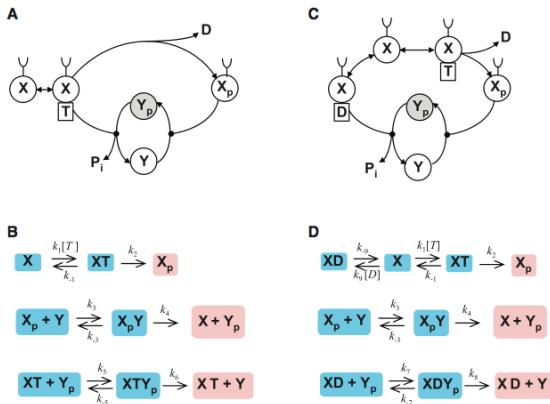


Fig. 2. The EnvZ-OmpR system. **(A)** A schematic diagram of an EnvZ-OmpR model in which ATP is the cofactor in phospho-OmpR dephosphorylation. P_i denotes phosphate ion. **(B)** The mass-action model underlying **(A)**. $[T]$ denotes the ATP concentration, assumed fixed. Terminal nodes are colored pink, and nonterminal nodes are colored blue. **(C)** A schematic diagram of an EnvZ-OmpR model in which ADP is the cofactor in phospho-OmpR dephosphorylation. **(D)** The mass-action model underlying **(C)**. $[D]$ denotes the ADP concentration, assumed fixed.

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Big picture

Goal of chemical reaction network theory:

discover how the dynamics of the mathematical model depend upon properties of the reaction network.

Key point of research:

want results that are applicable to whole classes of reaction networks, not studying a single model.

Short (incomplete) history of chemical reaction network theory

Dates back to at least work of Horn, Jackson, Feinberg in 1972:

- ▶ Detailed balancing is not necessary for many nice results.
- ▶ Developed idea of **complex balancing**.

1970s: development of **deficiency theory** to predict dynamics of deterministic models based solely on easily checked network conditions (deficiency = 0 and weak reversibility).

2000s: many more people started to join this research area

1. Large focus on global attractor conjecture.
2. Focus on possibility of multiple equilibria or oscillations.
3. Beginning to be a focus on stochastic models (green fluorescent proteins, laser traps, etc.)

Reaction Networks: $\{\mathcal{S}, \mathcal{C}, \mathcal{R}\}$

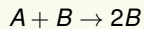
Example:



- ▶ $\mathcal{S} = \{A\}$.
- ▶ $\mathcal{C} = \{\emptyset, A\}$.
- ▶ $\mathcal{R} = \{\emptyset \rightarrow A, A \rightarrow \emptyset\}$.

Reaction Networks: $\{S, \mathcal{C}, \mathcal{R}\}$

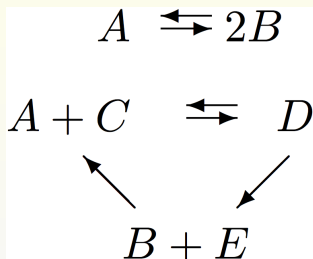
Example:



- ▶ $S = \{A, B\}$.
- ▶ $\mathcal{C} = \{A + B, 2B, B, A\}$.
- ▶ $\mathcal{R} = \{A + B \rightarrow 2B, B \rightarrow A\}$.

Reaction Networks: $\{\mathcal{S}, \mathcal{C}, \mathcal{R}\}$

Example:



Species: $\mathcal{S} = \{A, B, C, D, E\}$.

Complexes: $\mathcal{C} = \{A, 2B, A + C, D, B + E\}$.

Reactions:

$\mathcal{R} = \{A \rightarrow 2B, 2B \rightarrow A, A + C \rightarrow D, D \rightarrow A + C, D \rightarrow B + E, B + E \rightarrow A + C\}$.

Reaction Networks: $\{\mathcal{S}, \mathcal{C}, \mathcal{R}\}$

Definition

A **chemical reaction network**, $\{\mathcal{S}, \mathcal{C}, \mathcal{R}\}$, consists of:

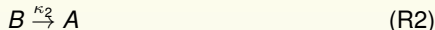
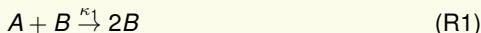
1. **Species**, $\mathcal{S} := \{S_1, \dots, S_d\}$: constituent molecules undergoing a series of chemical reactions.
2. **Complexes**, \mathcal{C} : linear combinations of the species representing those used, and produced, in each reaction.
3. A set of **reactions**, $\mathcal{R} := \{y_k \rightarrow y'_k\}$.

Denote **reaction vectors**

$$\zeta_k = y'_k - y_k.$$

Dynamics – deterministic

Example:



Let $x(t) \in \mathbb{R}_{\geq 0}^2$ give concentrations of molecules of A and B :

$$x'(t) = r_1(x(t)) \begin{bmatrix} -1 \\ 1 \end{bmatrix} + r_2(x(t)) \begin{bmatrix} 1 \\ -1 \end{bmatrix}.$$

Deterministic mass-action kinetics says:

$$r_1(x(t)) = \kappa_1 x_A(t) x_B(t), \quad \text{and} \quad r_2(x(t)) = \kappa_2 x_B(t).$$

so

$$x'_A(t) = -\kappa_1 x_A(t) x_B(t) + \kappa_2 x_B(t)$$

$$x'_B(t) = \kappa_1 x_A(t) x_B(t) - \kappa_2 x_B(t).$$

Dynamics – deterministic

Consider a general system with $\mathcal{S} = \{X_1, \dots, X_d\}$, and k th reaction



- The **rate** of k th reaction is $r_k : \mathbb{R}_{\geq 0}^d \rightarrow \mathbb{R}$.
- As before:

$$x'(t) = \sum_k r_k(x(t))(y'_k - y_k),$$

or

$$x(t) = x(0) + \sum_k \left(\int_0^t r_k(x(s)) ds \right) (y'_k - y_k).$$

Deterministic mass-action kinetics

Consider reaction



Then rate is

$$r_k(x) = \kappa_k x^{y_k} = \kappa_k \prod_{i=1}^d x_i^{y_{ki}}.$$

Example: If $S_1 \rightarrow \text{anything}$, then $r_k(x) = \kappa_k x_1$.

Example: If $S_1 + S_2 \rightarrow \text{anything}$, then $r_k(x) = \kappa_k x_1 x_2$.

Example: If $2S_2 \rightarrow \text{anything}$, then $r_k(x) = \kappa_k x_2^2$.

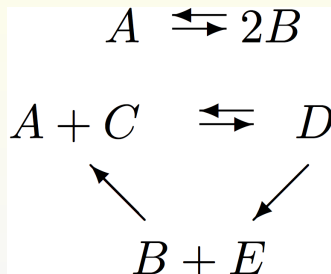
Example: If $3S_1 + 2S_2 + S_3 \rightarrow \text{anything}$, then $r_k(x) = \kappa_k x_1^3 x_2^2 x_3$.

Yields:

$$\dot{x} = \sum_k \kappa_k x^{y_k} (y'_k - y_k)$$

Dynamics – deterministic

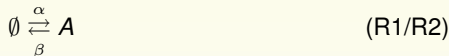
Example:



$$\begin{aligned} dc_A/dt &= -(\kappa_{A \rightarrow 2B})c_A + (\kappa_{2B \rightarrow A})c_B^2 - (\kappa_{A+C \rightarrow D})c_A c_C + (\kappa_{D \rightarrow A+C})c_D + (\kappa_{B+E \rightarrow A+C})c_B c_E \\ dc_B/dt &= 2(\kappa_{A \rightarrow 2B})c_A - 2(\kappa_{2B \rightarrow A})c_B^2 + (\kappa_{D \rightarrow B+E})c_D - (\kappa_{B+E \rightarrow A+C})c_B c_E \\ dc_C/dt &= -(\kappa_{A+C \rightarrow D})c_A c_C + (\kappa_{D \rightarrow A+C})c_D + (\kappa_{B+E \rightarrow A+C})c_B c_E \\ dc_D/dt &= (\kappa_{A+C \rightarrow D})c_A c_C - (\kappa_{D \rightarrow A+C})c_D - (\kappa_{D \rightarrow B+E})c_D \\ dc_E/dt &= (\kappa_{D \rightarrow B+E})c_D - (\kappa_{B+E \rightarrow A+C})c_B c_E . \end{aligned}$$

Dynamics: discrete – stochastic

Example:



Let $X(t)$ represent # molecules of A at time $t \geq 0$.

Suppose rate of reactions are:

$$\lambda_1(X(t)) = \alpha$$

$$\lambda_2(X(t)) = \beta X(t).$$

This means

$$P(\text{reaction } \emptyset \rightarrow A \text{ happens in next } \Delta t) = \alpha \Delta t + o(\Delta t)$$

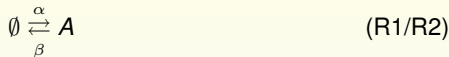
$$P(\text{reaction } A \rightarrow \emptyset \text{ happens in next } \Delta t) = \beta X(t) \Delta t + o(\Delta t).$$

This describes a model with **exponential holding times**.

There are multiple ways to specify this model.

Dynamics: discrete – stochastic

Example:



Let $X(t)$ represent # molecules of A at time $t \geq 0$.

$$X(t) = X(0) + R_1(t) - R_2(t).$$

For stochastic (Markov) models can take

$$R_1(t) = Y_1(\alpha t)$$

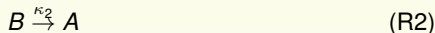
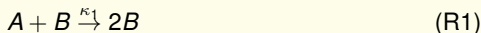
$$R_2(t) = Y_2\left(\beta \int_0^t X_A(s) ds\right)$$

where Y_1, Y_2 are independent unit-rate Poisson processes.

$$X(t) = X(0) + Y_1(\alpha t) - Y_2\left(\beta \int_0^t X_A(s) ds\right).$$

Dynamics: discrete – stochastic

Example:



Let $X(t) \in \mathbb{Z}_{\geq 0}^2$ give counts of # molecules of A and B :

$$\begin{aligned} X(t) &= X(0) + R_1(t) \left(\begin{bmatrix} 0 \\ 2 \end{bmatrix} - \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right) + R_2(t) \left(\begin{bmatrix} 1 \\ 0 \end{bmatrix} - \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right) \\ &= X(0) + R_1(t) \begin{bmatrix} -1 \\ 1 \end{bmatrix} + R_2(t) \begin{bmatrix} 1 \\ -1 \end{bmatrix}. \end{aligned}$$

For Markov models can take

$$R_1(t) = Y_1 \left(\kappa_1 \int_0^t X_A(s) X_B(s) ds \right)$$

$$R_2(t) = Y_2 \left(\kappa_2 \int_0^t X_B(s) ds \right)$$

where Y_1, Y_2 are independent unit-rate Poisson processes

$$X(t) = X(0) + Y_1 \left(\kappa_1 \int_0^t X_A(s) X_B(s) ds \right) \begin{bmatrix} -1 \\ 1 \end{bmatrix} + Y_2 \left(\kappa_2 \int_0^t X_B(s) ds \right) \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

Dynamics: discrete – stochastic

Consider a general system with $\mathcal{S} = \{X_1, \dots, X_d\}$, and k th reaction



- The **rate** (or **intensity** or **propensity**) of k th reaction is $\lambda_k : \mathbb{Z}_{\geq 0}^d \rightarrow \mathbb{R}$.
- As before:

$$X(t) = X(0) + \sum_k R_k(t)(y'_k - y_k),$$

with

$$X(t) = X(0) + \sum_k Y_k \left(\int_0^t \lambda_k(X(s)) ds \right) (y'_k - y_k),$$

Y_k are independent, unit-rate Poisson processes.

Stochastic mass-action kinetics

The standard intensity function chosen is **stochastic mass-action kinetics**:

$$\lambda_k(x) = \kappa_k \prod_{i=1}^d \frac{x_i!}{(x_i - y_{ik})!} 1_{\{x_i \geq y_{ik}\}}.$$

Example: If $S_1 \rightarrow \text{anything}$, then $\lambda_k(x) = \kappa_k x_1$.

Example: If $S_1 + S_2 \rightarrow \text{anything}$, then $\lambda_k(x) = \kappa_k x_1 x_2$.

Example: If $2S_2 \rightarrow \text{anything}$, then $\lambda_k(x) = \kappa_k x_2(x_2 - 1) \approx \kappa_k x_2^2$ if $x_2 \gg 1$.

- **Idea**: rate is **proportional to number of distinct subsets of the molecules present that can form the inputs for the reaction**.

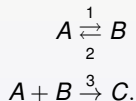
Dynamics: discrete – stochastic

Could just say that for $x \in \mathbb{Z}_{\geq 0}^d$,

$$x \rightarrow \begin{cases} x + y'_1 - y_1, & \text{with rate } \lambda_1(x) \\ x + y'_2 - y_2, & \text{with rate } \lambda_2(x) \\ \vdots \\ x + y'_K - y_K, & \text{with rate } \lambda_K(x) \end{cases}$$

where $y'_k - y_k \in \mathbb{Z}^d$.

Example



If $X(t) = [10, 8, 4]^T$, then rates are

$$\lambda_{A \rightarrow B}(X(t)) = 10, \quad \lambda_{B \rightarrow A}(X(t)) = 16, \quad \lambda_{A+B \rightarrow C}(X(t)) = 240.$$

Dynamics: discrete – stochastic

Model is a continuous time Markov chain with infinitesimal generator

$$\mathcal{A}f(x) = \sum_k \lambda_k(x)(f(x + \zeta_k) - f(x)).$$

where $\zeta_k = y'_k - y_k$.

Kolmogorov's forward equation (chemical master equation)

$$p'_t(x) = \sum_k \lambda_k(x - \zeta_k) p_t(x - \zeta_k) 1_{\{x - \zeta_k \in \mathbb{Z}_{\geq 0}^d\}} - p_t(x) \sum_k \lambda_k(x), \quad \forall x \in \mathbb{Z}_{\geq 0}^d$$

Stationary distribution π satisfies

$$0 = \sum_k \lambda_k(x - \zeta_k) \pi(x - \zeta_k) - \pi(x) \sum_k \lambda_k(x), \quad \forall x \in \mathbb{Z}_{\geq 0}^d$$

Example: population growth

Example

$$B \xrightarrow{1/3} 2B$$

with $X(0) = 10$.

Stochastic equation:

$$X(t) = 10 + Y \left(\int_0^t \frac{1}{3} X(s) ds \right).$$

Forward equation (master equation): For $x \in \{10, 11, \dots\}$

$$\frac{d}{dt} p_t(x) = \frac{1}{3} (x-1) p_t(x-1) 1_{\{x-1 \geq 10\}} - \frac{1}{3} x \cdot p_t(x)$$

i.e.

$$\frac{d}{dt} p_t(10) = -\frac{1}{3} \cdot 10 \cdot p_t(10)$$

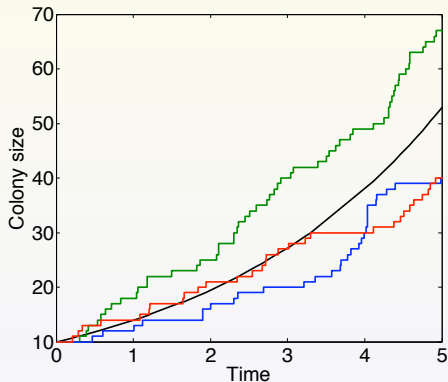
$$\frac{d}{dt} p_t(11) = \frac{1}{3} \cdot 10 \cdot p_t(10) - \frac{1}{3} \cdot 11 \cdot p_t(11)$$

$$\frac{d}{dt} p_t(12) = \frac{1}{3} \cdot 11 \cdot p_t(11) - \frac{1}{3} \cdot 12 \cdot p_t(12)$$

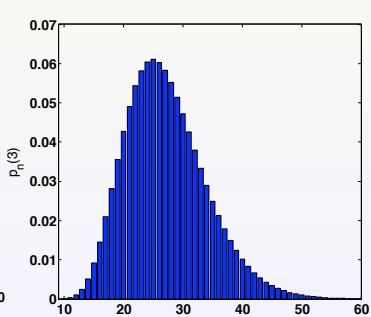
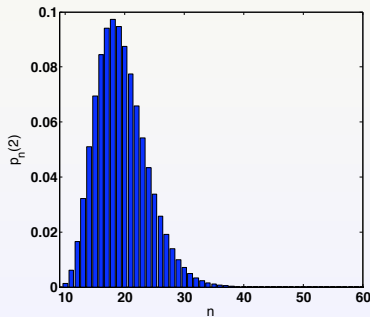
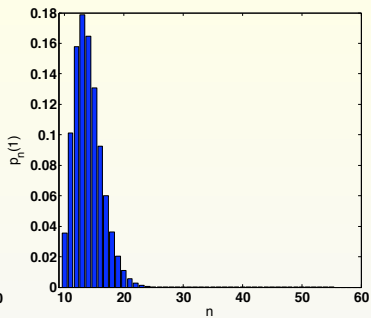
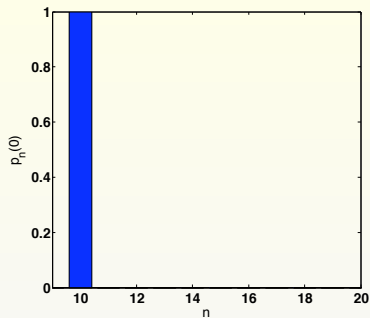
$$\vdots$$

Example: population growth

- Below is a plot of the solution of the deterministic system versus three different realizations of the stochastic system.



Example: population growth - evolution of distribution



Connection

Suppose V is a (large) scaling parameter and

- ▶ $X_i = O(V)$, and $X^V(t) \stackrel{\text{def}}{=} V^{-1} \cdot X(t)$,
- ▶ $\lambda_k(X(t)) = O(V)$

Then,

$$X^V(t) \approx \frac{1}{V} X_0 + \sum_k \frac{1}{V} Y_k \left(V \int_0^t \kappa_k X^V(s)^{y_k} ds \right) (y'_k - y_k)$$

LLN for Y_k says

$$\frac{1}{V} Y_k(Vu) \approx u \quad \left(\lim_{V \rightarrow \infty} \sup_{u \leq U} |V^{-1} Y_k(Vu) - u| = 0, \quad a.s. \right)$$

so a good approximation is solution to

$$x(t) = x(0) + \sum_k \int_0^t \kappa_k x(s)^{y_k} ds \cdot (y'_k - y_k),$$

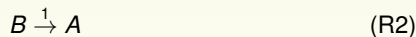
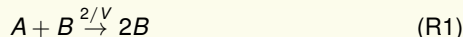
where

$$u^V = u_1^{v_1} \cdots u_d^{v_d},$$

is standard mass-action kinetics. [See Tom Kurtz's works....](#)

LLN: Example

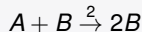
- ▶ Stochastic models:



with $X(0) = [3V, V]$ so that $[A^V, B^V] = X/V$ satisfies

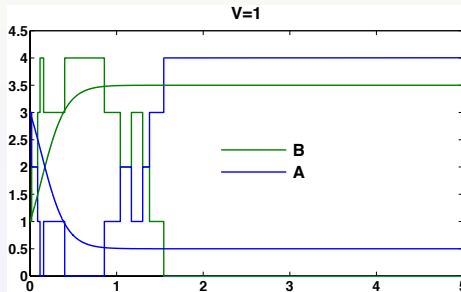
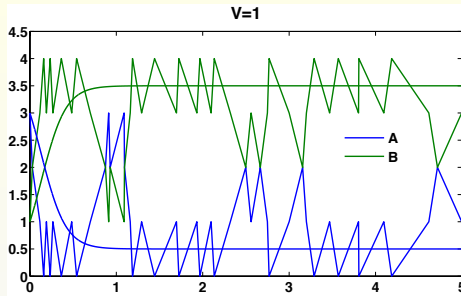
$$A^V(0) = 3, \quad B^V(0) = 1.$$

- ▶ ODE model of

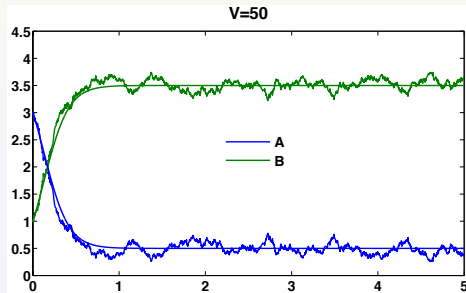
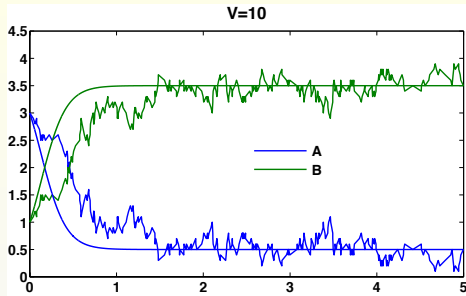


with $x(0) = [3, 1]$.

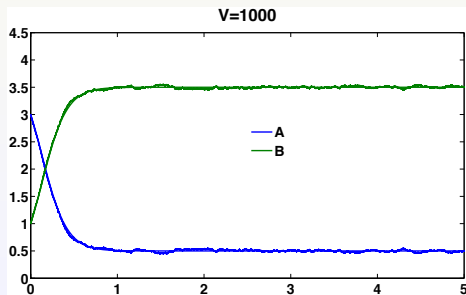
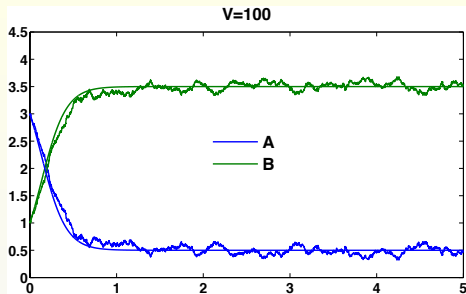
LLN: Example, $A + B \rightarrow 2B$ $B \rightarrow A$



LLN: Example, $A + B \rightarrow 2B$ $B \rightarrow A$



LLN: Example, $A + B \rightarrow 2B$ $B \rightarrow A$



What now?

So now you know what these models are.

Big question: Can we relate network structure to dynamics?

Deficiency zero theorem of Horn, Jackson, Feinberg

Theorem (Series of papers from 1972-1995)

Let $\{S, C, R\}$ be a chemical reaction network with deterministic mass-action kinetics. Suppose:

1. the network is *weakly reversible*, and
2. has a *deficiency of zero*.

Then, for any choice of rate constants κ_k , within each *positive stoichiometric compatibility class* there is precisely one equilibrium value c to the associated ODE system:

$$\sum_k \kappa_k c^{y_k} (y'_k - y_k) = 0,$$

and that equilibrium value is locally (globally?) asymptotically stable relative to its compatibility class.

Actually have stronger result: for each $\eta \in C$,

$$\sum_{k: y_k = \eta} \kappa_k c^{y_k} = \sum_{k: y'_k = \eta} \kappa_k c^{y_k}. \quad (1)$$

c is said to be a *complex balanced* equilibrium

Deficiency Zero Theorem - stochastic

Theorem (A., Craciun, Kurtz, 2010)

Let $\{S, C, R\}$ be a stochastically modeled reaction network with rate constants κ_K . Suppose:

1. the network is *weakly reversible*, and
2. has a *deficiency of zero*.

Then, for any irreducible communicating equivalence class, Γ , the stochastic system has a product form stationary distribution

$$\pi(x) = \frac{1}{Z_\Gamma} \prod_{i=1}^d e^{-c_i} \frac{c_i^{x_i}}{x_i!}, \quad x \in \Gamma, \quad (2)$$

where Z_Γ is a normalizing constant and c is a *complexed-balanced equilibrium* of the corresponding ODE.

David F. Anderson, Gheorghe Craciun, and Thomas G. Kurtz, *Product-form stationary distributions for deficiency zero chemical reaction networks*, Bulletin of Mathematical Biology, Vol. 72, No. 8, 1947 - 1970, 2010.

Stoichiometric compatibility classes

1. Note that for either model:

$$x(t) - x(0) = \sum_k \left(\int_0^t r_k(x(s)) ds \right) (y'_k - y_k) \in \text{span}_k \{y'_k - y_k\}$$

$$X(t) - X(0) = \sum_k Y_k \left(\int_0^t \lambda_k(X(s)) ds \right) (y'_k - y_k) \in \text{span}_k \{y'_k - y_k\}.$$

Definition.

$$S = \text{span}\{y'_k - y_k\}_k$$

is the **stoichiometric subspace** of the network. Let $\dim(S) = s$.

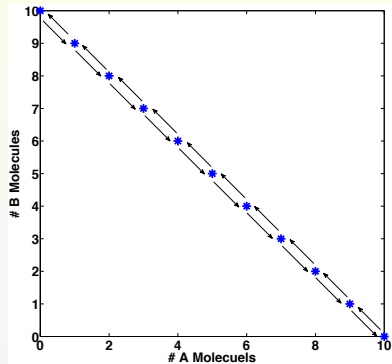
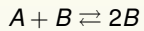
We see that solutions are bound to translations:

$$x(0) + S,$$

which are the **stoichiometric compatibility classes**.

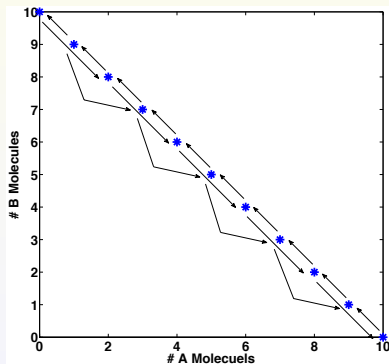
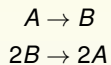
Compatibility classes

Example: Reaction network



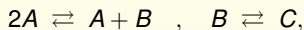
Compatibility classes

Reaction network



Compatibility classes

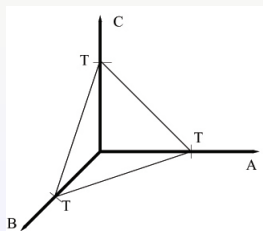
Reaction network



- $S \subset \mathbb{R}^3$ is the plane spanned by $(-1, 1, 0)^T$ and $(0, -1, 1)^T$.

For $T > 0$, the non-negative stoichiometric compatibility classes are two-dimensional triangles

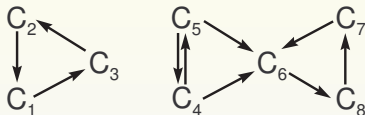
$$\left\{ (x_a, x_b, x_c) \in \mathbb{R}_{\geq 0}^3 \mid x_a + x_b + x_c = T \right\}$$



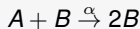
Connectivity

Definition

The connected components of the reaction network are called the *linkage classes*.



Example



(Linkage Class 1)



(Linkage Class 2)

Has two linkage classes.

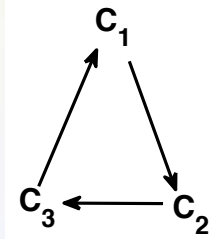
Connectivity

Definition

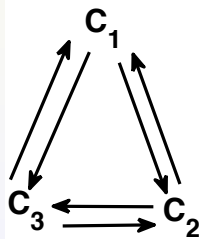
A chemical reaction network, $\{S, C, \mathcal{R}\}$, is said to be *weakly reversible* if each linkage class is strongly connected.

A network is called *reversible* if $y_k \rightarrow y'_k \in \mathcal{R} \implies y'_k \rightarrow y_k \in \mathcal{R}$.

Weakly Reversible

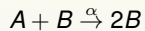


Reversible



Connectivity

The following is **not weakly reversible**:



(Linkage Class 1)



(Linkage Class 2)

Deficiency: in multiple ways!

Attempt 1:

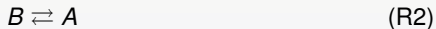
$$\text{deficiency of } \{S, C, R\} = \delta = n - \ell - s,$$

where

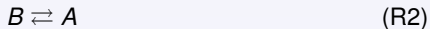
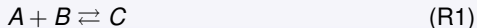
1. n = # of complexes.
2. ℓ = # of linkage classes.
3. s = dimension of span of reaction vectors.

So it is easy to check!

Example



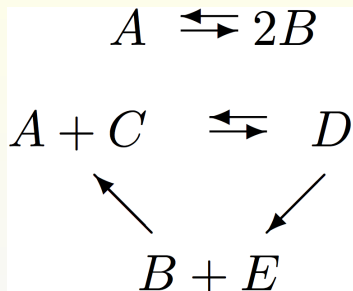
$n = 4, \ell = 2, s = 1 \implies \delta = 1$. But,



$n = 4, \ell = 2, s = 2 \implies \delta = 0$.

Deficiency

Example:



$$n = 5$$

$$\ell = 2$$

$$s = 3$$

$$\implies \delta = 5 - 2 - 3 = 0.$$

Deficiency: in multiple ways!

$$\text{deficiency of } \{\mathcal{S}, \mathcal{C}, \mathcal{R}\} = \delta = n - \ell - s,$$

Now you are probably thinking: Fiiiiine, but that was utterly useless to me. I have no idea what it means!

Attempt 2: a measure of nonlinearity (Technical but *very* useful)

We define

$$f(x) \stackrel{\text{def}}{=} \sum_k \kappa_k x^{y_k} (y'_k - y_k),$$

and will now find other functions, Y , A_κ , and Ψ for which

$$f(x) = Y \circ A_\kappa \circ \Psi(x).$$

Key point: Y and A_κ are matrices!

The hunt for linearity: $f = Y \circ A_\kappa \circ \Psi$

Example

$$A + B \xrightleftharpoons[\kappa_2]{\kappa_1} 2B \xrightleftharpoons[\kappa_4]{\kappa_3} 2A,$$

then

$$A_\kappa = \begin{bmatrix} -\kappa_1 & \kappa_2 & 0 \\ \kappa_1 & -(\kappa_2 + \kappa_3) & \kappa_4 \\ 0 & \kappa_3 & -\kappa_4 \end{bmatrix},$$

Note: Simply consider linear model:

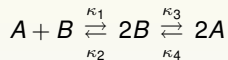
$$C_1 \xrightleftharpoons[\kappa_2]{\kappa_1} C_2 \xrightleftharpoons[\kappa_4]{\kappa_3} C_3,$$

then

$$\frac{d}{dt}C(t) = A_\kappa C(t).$$

The hunt for linearity: $f = Y \circ A_{\kappa} \circ \Psi$

Example



then

$$Y = \begin{bmatrix} 1 & 0 & 2 \\ 1 & 2 & 0 \end{bmatrix}$$

The hunt for linearity: $f = Y \circ A_\kappa \circ \Psi$

Example

$$A + B \xrightleftharpoons[\kappa_2]{\kappa_1} 2B \xrightleftharpoons[\kappa_4]{\kappa_3} 2A \quad \text{gives} \quad \Psi(x) = \begin{bmatrix} x_A x_B \\ x_B^2 \\ x_A^2 \end{bmatrix}$$

Thus,

$$\dot{x}(t) = \begin{bmatrix} 1 & 0 & 2 \\ 1 & 2 & 0 \end{bmatrix} \begin{bmatrix} -\kappa_1 & \kappa_2 & 0 \\ \kappa_1 & -(\kappa_2 + \kappa_3) & \kappa_4 \\ 0 & \kappa_3 & -\kappa_4 \end{bmatrix} \begin{bmatrix} x_A x_B \\ x_B^2 \\ x_A^2 \end{bmatrix}$$

Deficiency: attempt 2

$$f(x) = Y \circ A_{\kappa} \circ \Psi(x).$$

The deficiency of the model is

$$\delta = \dim(\ker Y \cap \text{image} A_{\kappa}).$$

You are probably thinking: Oh my, that did not help at all..... in fact, I think it made things **significantly worse**.

My response: think about fixed points to ODE model:

$$f(\bar{x}) = Y \circ A_{\kappa} \circ \Psi(\bar{x}) = 0$$

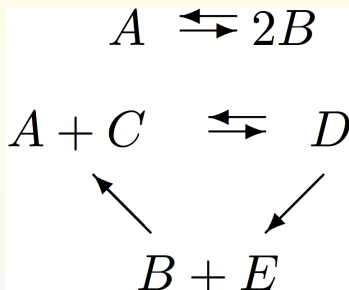
with $\bar{x} \in \mathbb{R}_{>0}^d$. This can happen in one of two ways:

$$(i) \quad A_{\kappa}(\Psi(\bar{x})) \in \ker Y \quad \text{or} \quad (ii) \quad \Psi(\bar{x}) \in \ker A_{\kappa}.$$

The second is a very nice condition: **complexed balanced equilibrium**

Deficiency

Example:



We know there is a \bar{c} satisfying,

$$\begin{aligned}\kappa_{A \rightarrow 2B} \bar{c}_A &= \kappa_{2B \rightarrow A} \bar{c}_B^2 \\ \kappa_{A+C \rightarrow D} \bar{c}_A \bar{c}_C &= \kappa_{D \rightarrow A+C} \bar{c}_D + \kappa_{B+E \rightarrow A+C} \bar{c}_B \bar{c}_E \\ \kappa_{D \rightarrow A+C} \bar{c}_D + \kappa_{D \rightarrow B+E} \bar{c}_D &= \kappa_{A+C \rightarrow D} \bar{c}_A \bar{c}_C \\ \kappa_{B+E \rightarrow A+C} \bar{c}_B \bar{c}_E &= \kappa_{D \rightarrow B+E} \bar{c}_D\end{aligned}$$

Generalizes **detailed balancing**.

Deficiency zero theorem of Horn, Jackson, Feinberg

Theorem (The Deficiency Zero Theorem - Deterministic)

Let $\{S, C, R\}$ be

1. weakly reversible, and
2. have a deficiency zero

Then, for any choice of rate constants κ_k , within the interior of each positive stoichiometric compatibility class there is precisely one equilibrium value c to the associated ODE system:

$$\sum_k \kappa_k c^{y_k} (y'_k - y_k) = 0,$$

and that equilibrium value is locally (globally?) asymptotically stable relative to its compatibility class.

Actually have stronger result: for each $\eta \in C$,

$$\sum_{k: y_k = \eta} \kappa_k c^{y_k} = \sum_{k: y'_k = \eta} \kappa_k c^{y_k}. \quad (3)$$

c is said to be a **complex balanced** equilibrium

Deficiency Zero Theorem - stochastic

Theorem (A., Craciun, Kurtz, 2010)

Let $\{S, C, R\}$ be a chemical reaction network with rate constants κ_k .

Suppose the associated ODE has a **complexed balanced equilibrium** c (or

1. the network is **weakly reversible**, and
2. has a **deficiency of zero**.

)

Then, for any irreducible communicating equivalence class, Γ , the stochastic system has a product form stationary distribution

$$\pi(x) = \frac{1}{Z_\Gamma} \prod_{i=1}^d e^{-c_i} \frac{c_i^{x_i}}{x_i!}, \quad x \in \Gamma, \quad (4)$$

where Z_Γ is a normalizing constant.

David F. Anderson, Gheorghe Craciun, and Thomas G. Kurtz, *Product-form stationary distributions for deficiency zero chemical reaction networks*, Bulletin of Mathematical Biology, Vol. 72, No. 8, 1947 - 1970, 2010.

Proof of stochastic version

Let c be a complexed balanced equilibrium for the deterministically modeled system and for $x \in \mathbb{Z}_{\geq 0}^d$ let

$$\pi(x) = \prod_{i=1}^d \frac{c_i^{x_i}}{x_i!} e^{-c_i} \quad \text{and} \quad \lambda_k(x) = \kappa_k \prod_{i=1}^d \frac{x_i!}{(x_i - y_{ki})!} 1_{\{x_i \geq y_{ki}\}}.$$

Plug $\pi(x)$ and $\lambda_k(x)$ into

$$\sum_k \pi(x - y'_k + y_k) \lambda_k(x - y'_k + y_k) = \pi(x) \sum_k \lambda_k(x).$$

Simplify (with some tricks) – ask offline if you want to see tricks.

Examples – (M/M/ ∞ queue)

$$\emptyset \xrightleftharpoons[\beta]{\alpha} A$$

Ode model:

$$\dot{x} = \alpha - \beta x \implies c = \frac{\alpha}{\beta}.$$

State space of stochastic model is

$$\{0, 1, 2, \dots\}$$

so

$$\pi(x) = e^{-\frac{\alpha}{\beta}} \cdot \frac{\left(\frac{\alpha}{\beta}\right)^x}{x!}.$$

Examples



ODE model:

$$\dot{x} = \alpha x - \beta x^2 \implies c = \frac{\alpha}{\beta}.$$

State space of stochastic model is

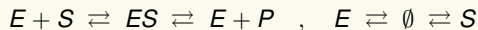
$$\{1, 2, \dots\}$$

So, for $x \in \{1, 2, \dots\}$

$$\pi(x) = \frac{1}{e^{\frac{\alpha}{\beta}} - 1} \cdot \frac{\left(\frac{\alpha}{\beta}\right)^x}{x!}$$

Enzyme kinetics

Consider the possible enzyme kinetics given by



Easy to check that state space is

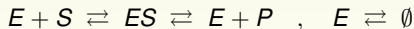
$$\Gamma = \mathbb{Z}_{\geq 0}^4$$

so in distributional equilibrium

- ▶ the specie numbers are independent and
- ▶ have Poisson distributions.

Enzyme kinetics

Consider the slightly different enzyme kinetics given by



- ▶ We see $S + ES + P = N$.
- ▶ In distributional equilibrium:
 - ▶ E has Poisson distribution,
 - ▶ S , ES , P have a multinomial distribution, and
 - ▶ E is independent from S , ES , and P .

Higher deficiency

What about the situation of $\delta \geq 1$? Tomorrow.

That is the story so far. Thanks!

Collaborators: Gheorghe Craciun and Tom Kurtz

Funding: Army Research Office, grant W911NF-14-1-0401.

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