

Math 322 Lecture 1 | 9/7/16

Reading: Haberman 1.1, 1.2, 1.5

Introduction to PDEs (partial differential equations)

3 Fundamental PDEs:

* Heat Equation (conduction)

$$\frac{\partial T(x,t)}{\partial t} = k \nabla^2 T(x,t) + \phi(x,t)$$

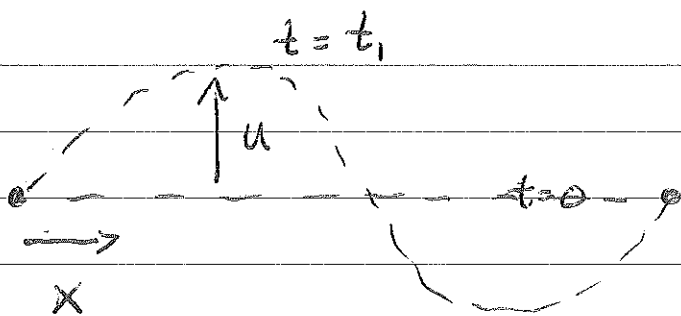
* Poisson's Equation (steady state heat eqn)

$$0 = k \nabla^2 T(x,t) + \phi(x,t)$$

* The Wave Equation

$$\frac{\partial^2 u(x,t)}{\partial t^2} = c^2 \nabla^2 u(x,t) + f(x,t)$$

1D



Remarks:

* $\nabla^2 = \nabla \circ \nabla$ divergence of the gradient

where does this come from physically speaking?

* Linear vs. Nonlinear wrt dependent variable(s)

All these examples are linear; significant for solution techniques

A nonlinear example

$$\frac{d\underline{u}}{dt} + (\underline{u} \circ \nabla) \underline{u} = -\frac{1}{\rho} \nabla \rho + \nu \nabla^2 \underline{u}$$

$\underline{u} = \underline{u}(\underline{x}, t)$ is fluid velocity

$p = p(\underline{x}, t)$ is fluid pressure

In 1D

$$\frac{du}{dt} + u \frac{du}{dx} = \nu \frac{d^2 u}{dx^2} \quad \text{Burger's Eqn.}$$

$$u = u(x, t)$$

* Homogeneous vs. Non-homogeneous

$$Q(x,t)=0, F(x,t)=0$$

$$Q(x,t) \neq 0, F(x,t) \neq 0$$

* Boundary conditions ; initial conditions ?

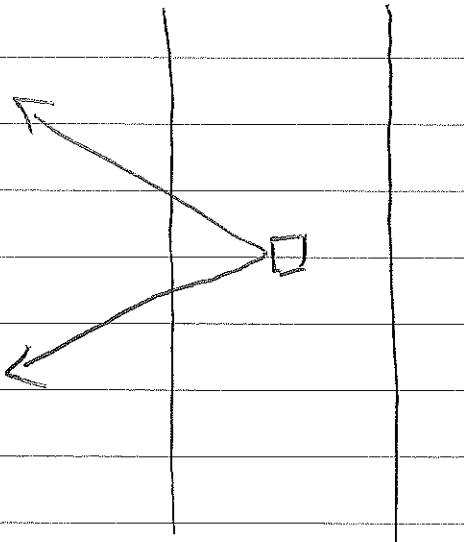
Start with the physical problem of heat conduction in a solid

Conduction in a solid \Rightarrow Heat Eqn.

Conduction and convection in a liquid/gas

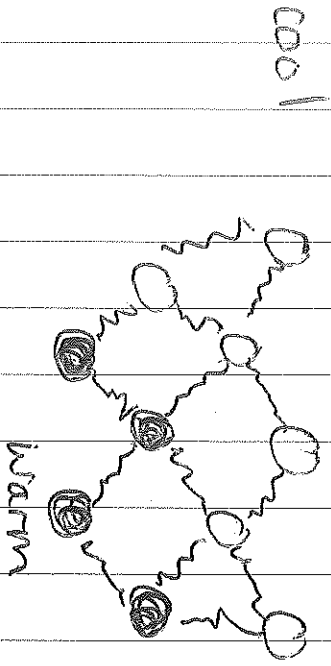
\Rightarrow Boussinesq Eqns.

Conduction in a solid



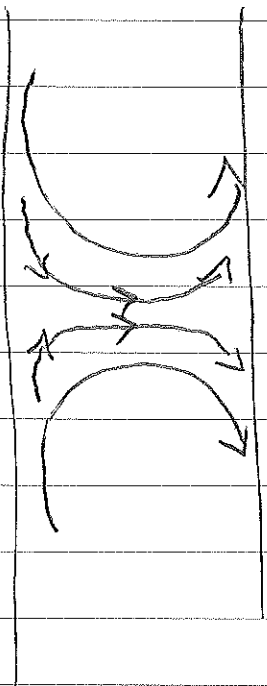
$z=H, T_c$

$z=0, T_h$



Diffusion is described
by the heat Eqn. ;
a linear equation

Convection in a fluid

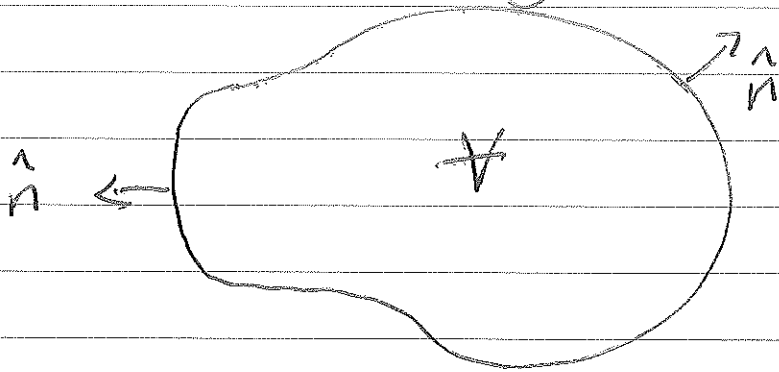


A fluid flows

Convection in a fluid
is described by the
Boussinesq equations ;
nonlinear equations

(5)

Consider an arbitrary volume of solid in 3D



V volume

\hat{n} is the outward normal to the surface

Conservation of Internal Energy :

rate of change of energy in V = energy in per unit time - energy leaving per unit time

+ energy generated inside V by sources/sinks per unit time

All terms are $\frac{\Delta E}{\Delta t}$

Dimensional Analysis :

[] \Rightarrow "dimension of"

internal energy : [energy] = [force \cdot distance]

$$[\text{energy}] = \left[\frac{m \cdot l}{t^2} \cdot l \right] = \left[\frac{m \cdot l^2}{t^2} \right]$$

e.g. $\frac{kg \cdot m^2}{s^2}$

} same dimensions as
 kinetic and potential
 $\frac{1}{2} m v^2$ and mgh

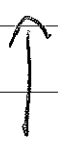
It will be convenient to work with

$e =$ internal energy density ; $e = e(x, t)$

$$[e] = \left[\frac{\text{energy}}{\text{volume}} \right] = \left[\frac{m \cdot l^2}{t^2} \frac{1}{l^3} \right] = \left[\frac{m}{l \cdot t^2} \right]$$

"Control Volume" formulation in terms of energy density:

$$\frac{d}{dt} \int_V e \, dV = \frac{\text{energy in}}{\text{unit time}} - \frac{\text{energy out}}{\text{unit time}} + \frac{\text{energy generated}}{\text{unit time}}$$



$\iiint dx dy dz$ in Cartesian coordinates

RHS terms

energy in - energy out
of unit time

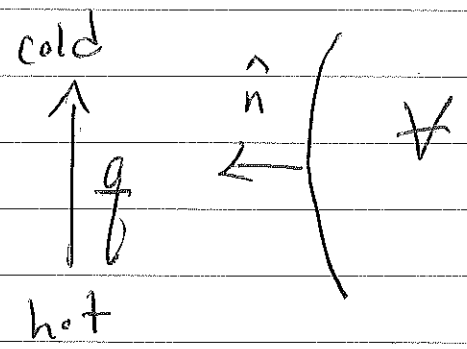
energy crossing the bandary of the volume, i.e.
the surface enclosing the volume =>

$$\int_A \mathbf{q} \cdot (-\hat{n}) dA$$

dA is a surface element

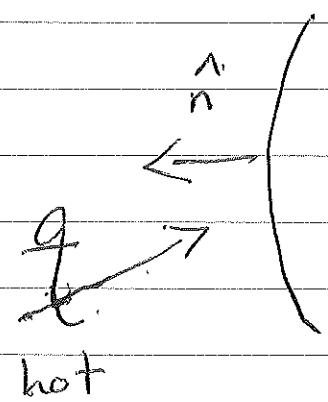
where \mathbf{q} is the heat flux vector

\mathbf{q} is a vector with magnitude and direction
because heat/energy flows from hot to cold



no energy enters \checkmark

$$\mathbf{q} \cdot (-\hat{n}) = 0$$



energy enters \checkmark

$$\mathbf{q} \cdot (-\hat{n}) \neq 0$$

The component of q that matters is in the direction of \hat{v} ($-\hat{n}$). The sign is so that "energy in" is positive and "energy out" is negative.

energy generated by sources/sinks
unit time

$$\int_V \rho(x,t) dV$$

(sources/sinks inside V)

Finally we arrive at

$$\frac{d}{dt} \int_V e dV = \oint_A q \cdot (-\hat{n}) dA$$

$$+ \int_V \rho(x,t) dV$$

$e(x,t)$ is energy density
 $q(x,t)$ is the heat flux vector

Next

1. Dimensional Analysis : What are the dimensions of the heat flux vector \mathbf{q} and the term representing sources/sinks \dot{q} ?

2. Can we write this equation in terms of temperature $T(\underline{x}, t)$

What is $e(\underline{x}, t)$, $\mathbf{q}(\underline{x}, t)$ in terms of $T(\underline{x}, t)$?

3. Then how do we go from the "Control Volume" equation to the PDE?