

First-Order Linear Differential Equations

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STANDARD FORM

Given two continuous functions $P(x)$ and $Q(x)$ of x defined on an interval $I \subseteq \mathbb{R}$ the corresponding **first-order linear differential equation** in **standard form** is the equation

$$\frac{dy}{dx} + P(x)y = Q(x).$$

When $Q(x) \equiv 0$ the differential equation is **homogeneous**.

Otherwise the differential equation is called **inhomogenous**.

When $P(x) \equiv 0$ the solution is the antiderivative $y(x) = \int Q(x) dx$.

SOLUTION OF THE HOMOGENEOUS EQUATION:

This equation is **separable** since it takes the form

$$\frac{dy}{dx} = -P(x)y.$$

For $y \neq 0$ we find the **one-parameter family** of solutions

$$\begin{aligned}\int \frac{dy}{y} &= -\int P(x) dx \\ \ln |y| &= -\int P(x) dx \\ |y| &= e^{-\int P(x) dx} \\ y(x) &= C e^{-\int P(x) dx}\end{aligned}$$

SOLUTION OF THE INHOMOGENEOUS EQUATION:

We try a solution of the form

$$y(x) = u(x) e^{-\int P(x) dx} = u(x) \left(e^{\int P(x) dx} \right)^{-1}.$$

Then

$$\begin{aligned} \frac{dy}{dx} &= \frac{du}{dx} e^{-\int P(x) dx} + u(x) \frac{d}{dx} \left(e^{-\int P(x) dx} \right) \\ &= \frac{du}{dx} e^{-\int P(x) dx} + u(x) e^{-\int P(x) dx} \frac{d}{dx} \left(-\int P(x) dx \right) \\ &= \frac{du}{dx} e^{-\int P(x) dx} + u(x) e^{-\int P(x) dx} (-P(x)) \\ &= \frac{du}{dx} e^{-\int P(x) dx} - P(x) y \end{aligned}$$

$$\frac{dy}{dx} + P(x)y = \frac{du}{dx} e^{-\int P(x) dx}$$

$$\frac{dy}{dx} + P(x)y = Q(x)$$

$$\frac{du}{dx} e^{-\int P(x) dx} = Q(x)$$

$$\frac{du}{dx} = Q(x) e^{\int P(x) dx}$$

$$u(x) = \int Q(x) e^{\int P(x) dx} dx$$

SUMMARY:

The general solution of the **first-order linear differential equation** takes the form

$$y(x) = e^{-\int P(x) dx} \int Q(x) e^{\int P(x) dx} dx .$$

The integration constant hidden in the notation $\int Q(x) e^{\int P(x) dx} dx$ produces a one-parameter family of solutions.

The analogous constant in $\int P(x) dx$ cancels from the formula.

Any one of the one-parameter family of functions $v(x) = e^{\int P(x) dx}$ appearing in the above solution formula is called an **integrating factor** for the differential equation.

STEPS TO FIND THE SOLUTION:

1. Bring the equation into the **normal form** $\frac{dy}{dx} + P(x)y = Q(x)$ and **identify** $P(x)$, $Q(x)$
2. Compute the **antiderivative** $\int P(x) dx$ and form the **integrating factor** $e^{\int P(x) dx}$
3. Transformed equation: $\frac{d}{dx} \left(e^{\int P(x) dx} y \right) = e^{\int P(x) dx} Q(x)$
4. Antiderive this equation: $e^{\int P(x) dx} y = \int Q(x) e^{\int P(x) dx} dx$
5. Solve for y : $y(x) = e^{-\int P(x) dx} \int Q(x) e^{\int P(x) dx} dx$

Simple Resistance-Inductance Electrical Circuits

Consider the RL-circuit shown in FIGURE 9.5 on page 654.

The current i flowing in this circuit at time t satisfies the following differential equation involving the **inductance** $L \neq 0$ in Henry, the **resistance** R in Ohm, the **voltage** V in Volt:

$$\frac{di}{dt} + \frac{R}{L}i = \frac{V}{L}.$$

In the simplest case, when L, R, V are **constant** in time, this linear differential equation has the integrating factor

$$e^{\int \frac{R}{L} dt} = e^{\frac{R}{L}t}.$$

The general solution is therefore given by

$$\begin{aligned}i(t) &= e^{-\int \frac{R}{L} dt} \int \frac{V}{L} e^{\int \frac{R}{L} dt} dt \\&= e^{-\frac{R}{L}t} \left(\int \frac{V}{L} e^{\frac{R}{L}t} dt \right) \\&= e^{-\frac{R}{L}t} \left(\frac{V L}{L R} e^{\frac{R}{L}t} + C \right) \\&= \frac{V}{R} + C e^{-\frac{R}{L}t}\end{aligned}$$

If $i(0) = 0$ the constant C equals $-\frac{V}{R}$ and the solution is a superposition of the **steady-state** and the **transient** solutions:

$$i(t) = \frac{V}{R} - \frac{V}{R} e^{-\frac{R}{L}t}.$$