

Stochastic models of biochemical systems

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Goal:

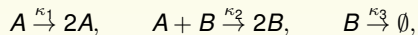
- ▶ give **broad introduction** to stochastic models of biochemical systems,
- ▶ with minimal technical details.

Outline

1. Construct useful representation for most common **continuous time Markov chain** model for population processes.
2. Discuss some computational methods – sensitivity analysis.
3. Discuss various approximate models for these CTMCs.

Example: ODE Lotka-Volterra predator-prey model

Think of A as a **prey** and B as a **predator**.



with $\kappa_1 = 2$, $\kappa_2 = .002$, $\kappa_3 = 2$.

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Think of A as a **prey** and B as a **predator**.

$$A \xrightarrow{\kappa_1} 2A, \quad A + B \xrightarrow{\kappa_2} 2B, \quad B \xrightarrow{\kappa_3} \emptyset,$$

with $\kappa_1 = 2$, $\kappa_2 = .002$, $\kappa_3 = 2$.

Deterministic model. Let $x(t) = [\# \text{ prey at } t, \# \text{ predator at } t]^T$

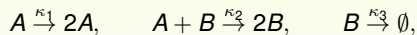
$$\dot{x}(t) = \kappa_1 x_1(t) \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \kappa_2 x_1(t)x_2(t) \begin{bmatrix} -1 \\ 1 \end{bmatrix} + \kappa_3 x_2(t) \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$

or

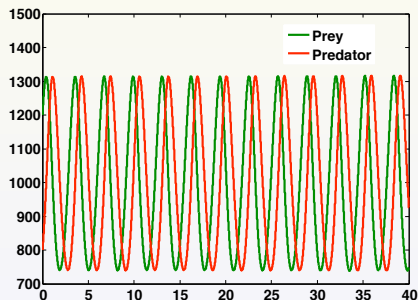
$$x(t) = x(0) + \kappa_1 \int_0^t x_1(s) ds \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \kappa_2 \int_0^t x_1(s)x_2(s) ds \begin{bmatrix} -1 \\ 1 \end{bmatrix} + \kappa_3 \int_0^t x_2(s) ds \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$

Lotka-Volterra

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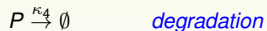
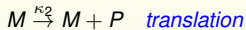
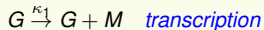


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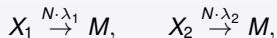
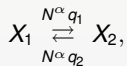
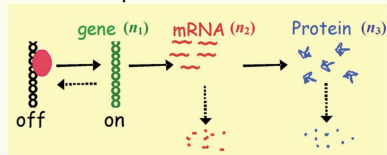


Biological example: transcription-translation

Gene transcription & translation:



Cartoon representation:

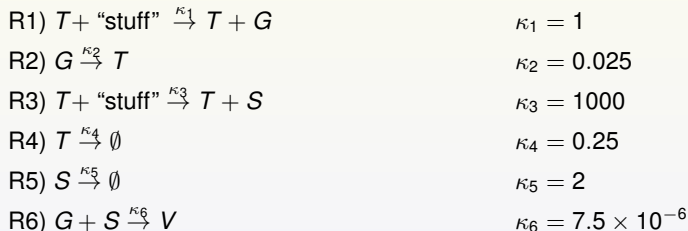


Another example: Viral infection

Let

1. T = viral template.
2. G = viral genome.
3. S = viral structure.
4. V = virus.

Reactions:



- ▶ R. Srivastava, L. You, J. Summers, and J. Yin, J. Theoret. Biol., 2002.
- ▶ E. Haseltine and J. Rawlings, J. Chem. Phys, 2002.
- ▶ K. Ball, T. Kurtz, L. Popovic, and G. Rempala, Annals of Applied Probability, 2006.
- ▶ W. E, D. Liu, and E. Vanden-Eijden, J. Comput. Phys, 2006.

Some examples

E. coli Heat Shock Response Model. 9 species, 18 reactions.

Reaction	Intensity	Reaction	Intensity
$\emptyset \rightarrow A_8$	4.00×10^0	$A_6 + A_8 \rightarrow A_9$	$3.62 \times 10^{-4} X_{A_6} X_{A_8}$
$A_2 \rightarrow A_3$	$7.00 \times 10^{-1} X_{A_2}$	$A_8 \rightarrow \emptyset$	$9.99 \times 10^{-5} X_{A_8}$
$A_3 \rightarrow A_2$	$1.30 \times 10^{-1} X_{A_3}$	$A_9 \rightarrow A_6 + A_8$	$4.40 \times 10^{-5} X_{A_9}$
$\emptyset \xrightarrow{A_1} A_2$	$7.00 \times 10^{-3} X_{A_1}$	$\emptyset \rightarrow A_1$	1.40×10^{-5}
$\text{stuff} + A_3 \rightarrow A_5 + A_2$	$6.30 \times 10^{-3} X_{A_3}$	$A_1 \rightarrow \emptyset$	$1.40 \times 10^{-6} X_{A_1}$
$\text{stuff} + A_3 \rightarrow A_4 + A_2$	$4.88 \times 10^{-3} X_{A_3}$	$A_7 \xrightarrow{A_4} A_6$	$1.42 \times 10^{-6} X_{A_4} X_{A_7}$
$\text{stuff} + A_3 \rightarrow A_6 + A_2$	$4.88 \times 10^{-3} X_{A_3}$	$A_5 \rightarrow \emptyset$	$1.80 \times 10^{-8} X_{A_5}$
$A_7 \rightarrow A_2 + A_6$	$4.40 \times 10^{-4} X_{A_7}$	$A_6 \rightarrow \emptyset$	$6.40 \times 10^{-10} X_{A_6}$
$A_2 + A_6 \rightarrow A_7$	$3.62 \times 10^{-4} X_{A_2} X_{A_6}$	$A_4 \rightarrow \emptyset$	$7.40 \times 10^{-11} X_{A_4}$

2

Modeling

1. These models (and much more complicated ones) have historically been predominantly modeled using ODEs.
2. However:
 - 2.1 there are often low numbers of molecules, which makes timing of reactions more random (less averaging),
 - 2.2 when a reaction occurs, the system **jumps** to new state by non-trivial amount: $1 \gg 0$.

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 - 2.1 there are often low numbers of molecules, which makes timing of reactions more random (less averaging),
 - 2.2 when a reaction occurs, the system **jumps** to new state by non-trivial amount: $1 \gg 0$.
3. Researchers (mostly) lived with these shortcomings until the late 1990s and early 2000s when it was shown ODE models can not capture important qualitative behavior of certain models:
 - ▶ λ -phage lysis-lysogeny decision mechanism (Arkin-McAdams 1998).
 - ▶ Green fluorescent protein.

ODEs were often the **wrong** modeling choice.

Specifying infinitesimal behavior

Q: **What is a better modeling choice?** Should be

1. **discrete space**, since counting molecules, and
2. **stochastic dynamics**.

Let's return to development of ODEs.

An ordinary differential equation is specified by describing how a function should vary over a small period of time

$$X(t + \Delta t) - X(t) \approx F(X(t))\Delta t$$

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$$X(t + \Delta t) - X(t) \approx F(X(t))\Delta t$$

A more precise description (consider a telescoping sum)

$$X(t) = X(0) + \int_0^t F(X(s))ds$$

Infinitesimal behavior for jump processes

We are interested in functions that are piecewise constant and random.

Changes, when they occur, won't be small. If “reaction k ” occurs at time t ,

$$X(t) - X(t-) = \zeta_k \in \mathbb{Z}^d$$

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$$X(t) - X(t-) = \zeta_k \in \mathbb{Z}^d$$

What is small? **The probability of seeing a jump of a particular size.**

$$P\{X(t + \Delta t) - X(t) = \zeta_k \mid \mathcal{F}_t\} \approx \lambda_{\zeta_k}(t)\Delta t$$

Question: Can we specify the λ_{ζ_k} in some way that determines X ?

- ▶ For the ODE, F depended on X .
- ▶ Maybe λ_{ζ_k} should depend on X ?

Simple model

For example, consider the simple system



where one molecule each of A and B is being converted to one of C .

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Intuition for standard stochastic model:

$$P\{\text{reaction occurs in } (t, t + \Delta t] | \mathcal{F}_t\} \approx \kappa X_A(t) X_B(t) \Delta t$$

where

- ▶ κ is a positive constant, the **reaction rate constant**.
- ▶ \mathcal{F}_t is all the information pertaining to the process up through time t .

Can we specify a reasonable model satisfying this assumption?

Background information: The Poisson process

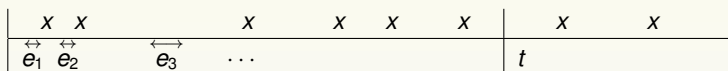
Will view a Poisson process, $Y(\cdot)$, through the lens of an underlying **point process**.

(a) Let $\{e_i\}$ be i.i.d. **exponential random variables** with parameter one.

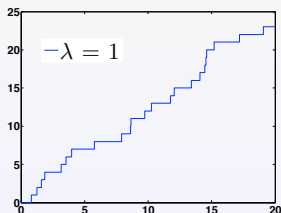
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- (a) Let $\{e_i\}$ be i.i.d. **exponential random variables** with parameter one.
- (b) Now, put points down on a line with spacing equal to the e_i :



- ▶ Let $Y_1(t)$ denote the number of points hit by time t .
- ▶ In the figure above, $Y_1(t) = 6$.

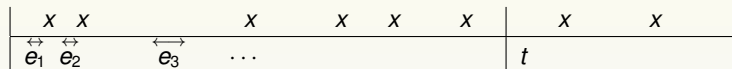


The Poisson process

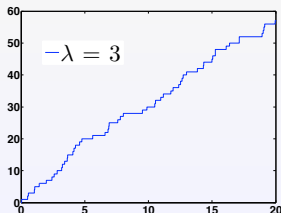
Let

- ▶ Y_1 be a unit rate Poisson process.
- ▶ Define $Y_\lambda(t) \equiv Y_1(\lambda t)$,

Then Y_λ is a Poisson process with parameter λ .



Intuition: The Poisson process with rate λ is simply the number of points hit (of the unit-rate point process) when we run along the time frame at **rate λ** .



The Poisson process

There is no reason λ needs to be constant in time, in which case

$$Y_\lambda(t) \equiv Y \left(\int_0^t \lambda(s) ds \right)$$

is a non-homogeneous Poisson process with **propensity/intensity** $\lambda(t) \geq 0$.

Thus

$$P\{Y_\lambda(t + \Delta t) - Y_\lambda(t) > 0 | \mathcal{F}_t\} = 1 - \exp \left\{ - \int_t^{t+\Delta t} \lambda(s) ds \right\} \approx \lambda(t) \Delta t.$$

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Points:

1. We have “**changed time**” to convert a unit-rate Poisson process to one which has **rate** or **intensity** or propensity $\lambda(t)$.
2. Will use similar time changes of unit-rate processes to build models of interest.

Return to models of interest

Consider the simple system



where one molecule each of A and B is being converted to one of C .

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$$P\{\text{reaction occurs in } (t, t + \Delta t] | \mathcal{F}_t\} \approx \kappa X_A(t) X_B(t) \Delta t$$

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Models of interest



Simple book-keeping says: if

$$X(t) = \begin{bmatrix} X_A(t) \\ X_B(t) \\ X_C(t) \end{bmatrix}$$

gives the state at time t , then

$$X(t) = X(0) + R(t) \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix},$$

where

- ▶ $R(t)$ is the # of times the reaction has occurred by time t and
- ▶ $X(0)$ is the initial condition.

Goal: represent $R(t)$ in terms of **Poisson process**.

Models of interest

Recall that for $A + B \rightarrow C$ our intuition was to specify infinitesimal behavior

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and that for a counting process with specified intensity $\lambda(t)$ we have

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This suggests we can model

$$R(t) = Y \left(\int_0^t \kappa X_A(s) X_B(s) ds \right)$$

where Y is a **unit-rate** Poisson process.

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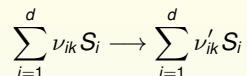
Hence

$$\begin{pmatrix} X_A(t) \\ X_B(t) \\ X_C(t) \end{pmatrix} \equiv X(t) = X(0) + \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix} Y \left(\int_0^t \kappa X_A(s) X_B(s) ds \right).$$

This equation uniquely determines X for all $t \geq 0$.

Build up model: Random time change representation of Kurtz

- Now consider a **network** of reactions involving d **chemical species**, S_1, \dots, S_d :



Denote reaction vector as

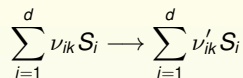
$$\zeta_k = \nu'_k - \nu_k,$$

so that if reaction k occurs at time t

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- The **intensity** (or **propensity**) of k th reaction is $\lambda_k : \mathbb{Z}_{\geq 0}^d \rightarrow \mathbb{R}$.
- By analogy with before:

$$X(t) = X(0) + \sum_k R_k(t) \zeta_k,$$

with

$$X(t) = X(0) + \sum_k Y_k \left(\int_0^t \lambda_k(X(s)) ds \right) \zeta_k,$$

Y_k are independent, unit-rate Poisson processes.

Mass-action kinetics

The standard intensity function chosen is **mass-action kinetics**:

$$\lambda_k(\mathbf{x}) = \kappa_k \left(\prod_i \nu_{ik}! \right) \binom{\mathbf{x}}{\nu_k} = \kappa_k \prod_i \frac{x_i!}{(x_i - \nu_{ik})!}.$$

Example: If $S_1 \rightarrow \text{anything}$, then $\lambda_k(\mathbf{x}) = \kappa_k x_1$.

Example: If $S_1 + S_2 \rightarrow \text{anything}$, then $\lambda_k(\mathbf{x}) = \kappa_k x_1 x_2$.

Example: If $2S_2 \rightarrow \text{anything}$, then $\lambda_k(\mathbf{x}) = \kappa_k x_2(x_2 - 1)$.

Other ways to understand model

The **infinitesimal generator** of a Markov process determines the process:

$$\mathcal{A}f(x) \stackrel{\text{def}}{=} \lim_{h \rightarrow 0} \frac{1}{h} [\mathbb{E}_x f(X(h)) - f(x)]$$

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Other ways to understand model

And we have Dynkin's formula (See [Ethier and Kurtz, 1986, Ch. 1](#))

$$\mathbb{E}f(X(t)) - f(X_0) = \mathbb{E} \int_0^t \mathcal{A}f(X(s)) ds,$$

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Letting $f(y) = 1_x(y)$, above so that

$$\mathbb{E}[f(X(t))] = P\{X(t) = x\} = p_x(t),$$

gives **Kolmogorov forward equation** (**chemical master equation**)

$$p'_t(x) = \sum_k \lambda(x - \zeta_k) p_t(x - \zeta_k) - p_t(x) \sum_k \lambda_k(x)$$

Equivalence of formulations

We now have three ways of making the infinitesimal specification

$$P\{X(t + \Delta t) - X(t) = \xi_k | \mathcal{F}_t^X\} \approx \lambda_k(X(t))\Delta t$$

precise:

1. The stochastic equation:

$$X(t) = X(0) + \sum_k Y_k \left(\int_0^t \lambda_k(X(s)) ds \right) \zeta_k$$

2. The process is Markov with infinitesimal generator

$$(\mathcal{A}f)(x) = \sum_k \lambda_k(x)(f(x + \zeta_k) - f(x))$$

3. The master (forward) equation for the probability distributions:

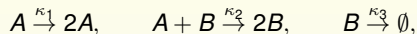
$$p'_x(t) = \sum_k \lambda_k(x - \zeta_k) p_t(x - \zeta_k) - p_t(x) \sum_k \lambda_k(x)$$

Fortunately, if the solution of the stochastic equation doesn't blow up, the three are equivalent.

This model is an example of a **continuous time Markov chain**.

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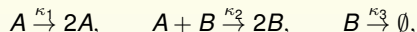
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Deterministic model. Let $x(t) = [\text{\#prey}, \text{\#predators}]^T$

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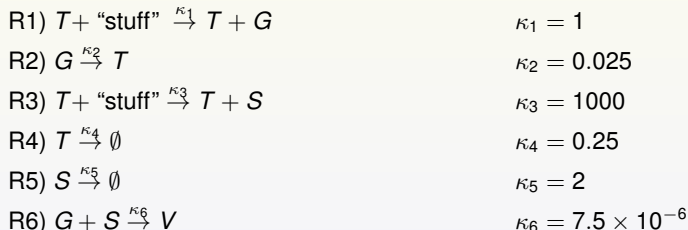
$$\begin{aligned} X(t) = X(0) &+ Y_1 \left(\kappa_1 \int_0^t X_1(s) ds \right) \begin{bmatrix} 1 \\ 0 \end{bmatrix} + Y_2 \left(\kappa_2 \int_0^t X_1(s)X_2(s) ds \right) \begin{bmatrix} -1 \\ 1 \end{bmatrix} \\ &+ Y_3 \left(\kappa_3 \int_0^t X_2(s) ds \right) \begin{bmatrix} 0 \\ -1 \end{bmatrix} \end{aligned}$$

Another example: Viral infection

Let

1. T = viral template.
2. G = viral genome.
3. S = viral structure.
4. V = virus.

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Another example: Viral infection

Stochastic equations for $X = (X_G, X_S, X_T, X_V)$ are

$$X_1(t) = X_1(0) + Y_1 \left(\int_0^t X_3(s) ds \right) - Y_2 \left(0.025 \int_0^t X_1(s) ds \right) \\ - Y_6 \left(7.5 \times 10^{-6} \int_0^t X_1(s) X_2(s) ds \right)$$

$$X_2(t) = X_2(0) + Y_3 \left(1000 \int_0^t X_3(s) ds \right) - Y_5 \left(2 \int_0^t X_2(s) ds \right) \\ - Y_6 \left(7.5 \times 10^{-6} \int_0^t X_1(s) X_2(s) ds \right)$$

$$X_3(t) = X_3(0) + Y_2 \left(0.025 \int_0^t X_1(s) ds \right) - Y_4 \left(0.25 \int_0^t X_3(s) ds \right)$$

$$X_4(t) = X_4(0) + Y_6 \left(7.5 \times 10^{-6} \int_0^t X_1(s) X_2(s) ds \right).$$

Computational methods

These are continuous time Markov chains!

Simulation/computation should be easy.

The most common simulation methods include

1. **Gillespie's Algorithm** – Answer **where** and **when** independently.
2. The **next reaction method** of Gibson and Bruck.
3. Each is an example of **discrete event simulation**.

Numerical methods

Each exact method produces sample paths that can approximate values such as (which I will talk about tomorrow at CWI)

$$\mathbb{E}f(X(t)) \approx \frac{1}{n} \sum_{i=1}^n f(X_{[i]}(t))$$

For example,

1. Means – expected virus yield.
2. Variances.
3. Probabilities.

or **sensitivities**

$$\frac{d}{d\theta} \mathbb{E}f(\theta, X^\theta(t)).$$

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$$\frac{d}{d\theta} \mathbb{E}f(\theta, X^\theta(t)).$$

Problem: solving using these algorithms can be computationally expensive:

1. Each path may require significant number of computational steps.
2. → May require significant number of paths.

Solution: Need to use novel stochastic representations to get good methods.

Specific computational problem: Gradient estimation/sensitivity analysis

We have

$$X^\theta(t) = X^\theta(0) + \sum_k Y_k \left(\int_0^t \lambda_k(\theta, X^\theta(s)) ds \right) \zeta_k,$$

with $\theta \in \mathbb{R}^s$, and we define

$$J(\theta) = \mathbb{E}f(\theta, X^\theta(t)).$$

We know how to estimate $J(\theta)$ using Monte Carlo.

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However, what if we want

$$J'(\theta) = \frac{d}{d\theta} \mathbb{E}f(\theta, X^\theta(t)).$$

Thus, we want to know how sensitive our statistic is to perturbations in θ .

Tells us, for example:

1. Robustness of system to perturbations in parameters.
2. Which parameters we need to estimate well from data, etc.

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There are multiple methods. We will consider:

- ▶ **Finite differences.**

Finite differencing

This method is pretty straightforward and is therefore used most.

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Simply note that

$$J'(\theta) = \frac{J(\theta + \epsilon) - J(\theta)}{\epsilon} + O(\epsilon) = \mathbb{E} \left[\frac{f(\theta + \epsilon, X^{\theta+\epsilon}(t)) - f(\theta, X^\theta(t))}{\epsilon} \right] + O(\epsilon).$$

Centered differencing reduces bias to $O(\epsilon^2)$.

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Centered differencing reduces bias to $O(\epsilon^2)$.

The usual finite difference estimator is

$$D_N(\epsilon) = \frac{1}{N} \sum_{i=1}^N \frac{f(\theta + \epsilon, X_{[i]}^{\theta+\epsilon}(t)) - f(\theta, X_{[i]}^\theta(t))}{\epsilon}$$

Letting $\delta > 0$ be some desired accuracy (for confidence interval), we need N so that

$$\sqrt{\text{Var}(D_N(\epsilon))} \leq \delta.$$

Finite differencing

Want

$$\sqrt{\text{Var}(D_N(\epsilon))} \leq \delta.$$

with

$$D_N(\epsilon) = \frac{1}{N} \sum_{i=1}^N \frac{f(\theta, X_{[i]}^{\theta+\epsilon}(t)) - f(\theta, X_{[i]}^{\theta}(t))}{\epsilon}$$

If paths generated independently, then

$$\begin{aligned}\text{Var}(D_N(\epsilon)) &= N^{-1} \epsilon^{-2} \text{Var}(f(\theta, X_{[1]}^{\theta+\epsilon}(t)) - f(\theta, X_{[1]}^{\theta}(t))) \\ &= O(N^{-1} \epsilon^{-2}),\end{aligned}$$

implying

$$\frac{1}{\sqrt{N}} \frac{1}{\epsilon} = O(\delta) \implies N = O(\epsilon^{-2} \delta^{-2})$$

Terrible. Worse than expectations.

How about **common random numbers** for **variance reduction**?

Common random numbers

It's exactly what it sounds like. Reuse the random numbers used in the generation of

$$X_{[i]}^{\theta+\epsilon}(t) \quad \text{and} \quad X_{[i]}^{\theta}(t).$$

Why?

Common random numbers

It's exactly what it sounds like. Reuse the random numbers used in the generation of

$$X_{[i]}^{\theta+\epsilon}(t) \quad \text{and} \quad X_{[i]}^{\theta}(t).$$

Why? Because:

$$\begin{aligned} \text{Var}(f(\theta, X_{[i]}^{\theta+\epsilon}(t)) - f(\theta, X_{[i]}^{\theta}(t))) &= \text{Var}(f(\theta, X_{[i]}^{\theta+\epsilon}(t))) + \text{Var}(f(\theta, X_{[i]}^{\theta}(t))) \\ &\quad - 2\text{Cov}(f(\theta, X_{[i]}^{\theta+\epsilon}(t)), f(\theta, X_{[i]}^{\theta}(t))). \end{aligned}$$

So, if we can “couple” the random variables, we can get a variance reduction! Sometimes substantial.

Common random numbers

- ▶ In the context of Gillespie's algorithm, we simply reuse all the same random numbers (uniforms).
- ▶ This can be achieved simply by setting the “seed” of the random number generator before generating $X^{\theta+\epsilon}$ and X^θ .

Common random numbers

CRN + Gillespie is good idea.

1. Costs little in terms of implementation.
2. Variance reduction and gains in efficiency can be **huge**.

Thus, it is probably the most common method used today.

But:

- ▶ Over time, the processes decouple, often completely.

Can we do better?

Coupling

Using common random numbers in previous fashion is a way of “coupling” the two processes together.

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Is there a natural way to couple processes using random time change? Can we couple the Poisson processes?

Answer: yes. Multiple ways. I will show one which works very well.

How do we generate processes simultaneously

Suppose I want to generate:

- ▶ A Poisson process with intensity 13.1.
- ▶ A Poisson process with intensity 13.

How do we generate processes simultaneously

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- ▶ We could let Y_1 and Y_2 be independent, unit-rate Poisson processes, and set

$$Z_{13.1}(t) = Y_1(13.1t),$$

$$Z_{13}(t) = Y_2(13t),$$

Using this representation, these processes are independent and, hence, not coupled.

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Using this representation, these processes are independent and, hence, not coupled.

The variance of difference is large:

$$\begin{aligned}\text{Var}(Z_{13.1}(t) - Z_{13}(t)) &= \text{Var}(Y_1(13.1t)) + \text{Var}(Y_2(13t)) \\ &= 26.1t.\end{aligned}$$

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$$\begin{aligned}Z_{13.1}(t) &= Y_1(13t) + Y_2(0.1t) \\ Z_{13}(t) &= Y_1(13t),\end{aligned}$$

The variance of difference is much smaller:

$$\text{Var}(Z_{13.1}(t) - Z_{13}(t)) = \text{Var}(Y_2(0.1t)) = 0.1t.$$

Using a fact: sum of homogeneous Poisson process is again a Poisson process.

How do we generate processes simultaneously

More generally, suppose we want

1. non-homogeneous Poisson process with intensity $f(t)$ and
2. non-homogeneous Poisson process with intensity $g(t)$.

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1. non-homogeneous Poisson process with intensity $f(t)$ and
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We can let Y_1 , Y_2 , and Y_3 be independent, unit-rate Poisson processes and define

$$Z_f(t) = Y_1 \left(\int_0^t f(s) \wedge g(s) ds \right) + Y_2 \left(\int_0^t f(s) - (f(s) \wedge g(s)) ds \right),$$
$$Z_g(t) = Y_1 \left(\int_0^t f(s) \wedge g(s) ds \right) + Y_3 \left(\int_0^t g(s) - (f(s) \wedge g(s)) ds \right),$$

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where we are using that, for example,

$$Y_1 \left(\int_0^t f(s) \wedge g(s) ds \right) + Y_2 \left(\int_0^t f(s) - (f(s) \wedge g(s)) ds \right) = Y \left(\int_0^t f(s) ds \right),$$

where Y is a unit rate Poisson process.

Parameter sensitivities.

Couple the processes.

$$\begin{aligned} X^{\theta+\epsilon}(t) &= X^{\theta+\epsilon}(0) + \sum_k Y_{k,1} \left(\int_0^t \lambda_k^{\theta+\epsilon}(X^{\theta+\epsilon}(s)) \wedge \lambda_k^\theta(X^\theta(s)) ds \right) \zeta_k \\ &\quad + \sum_k Y_{k,2} \left(\int_0^t \lambda_k^{\theta+\epsilon}(X^{\theta+\epsilon}(s)) - \lambda_k^{\theta+\epsilon}(X^{\theta+\epsilon}(s)) \wedge \lambda_k^\theta(X^\theta(s)) ds \right) \zeta_k \end{aligned}$$

$$\begin{aligned} X^\theta(t) &= X^\theta(0) + \sum_k Y_{k,1} \left(\int_0^t \lambda_k^{\theta+\epsilon}(X^{\theta+\epsilon}(s)) \wedge \lambda_k^\theta(X^\theta(s)) ds \right) \zeta_k \\ &\quad + \sum_k Y_{k,3} \left(\int_0^t \lambda_k^\theta(X^\theta(s)) - \lambda_k^{\theta+\epsilon}(X^{\theta+\epsilon}(s)) \wedge \lambda_k^\theta(X^\theta(s)) ds \right) \zeta_k, \end{aligned}$$

Parameter sensitivities.

Theorem

³ Suppose $(X^{\theta+\epsilon}, X^\theta)$ satisfy coupling. Then, for any $T > 0$ there is a $C_{T,f} > 0$ for which

$$\mathbb{E} \sup_{t \leq T} \left(f(\theta + \epsilon, X^{\theta+\epsilon}(t)) - f(\theta, X^\theta(t)) \right)^2 \leq C_{T,f} \epsilon.$$

³David F. Anderson, *An Efficient Finite Difference Method for Parameter Sensitivities of Continuous Time Markov Chains*, SIAM: Journal on Numerical Analysis, Vol. 50, No. 5, 2012.

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This lowers variance of estimator from

$$O(N^{-1} \epsilon^{-2}),$$

to

$$O(N^{-1} \epsilon^{-1}).$$

Lowered by order of magnitude (in ϵ).

Point: a deeper mathematical understanding led to better computational method.

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Analysis

Theorem

Suppose $(X^{\theta+\epsilon}, X^\theta)$ satisfy coupling. Then, for any $T > 0$ there is a $C_{T,f} > 0$ for which

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Proof:

Analysis

Theorem

Suppose $(X^{\theta+\epsilon}, X^\theta)$ satisfy coupling. Then, for any $T > 0$ there is a $C_{T,f} > 0$ for which

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Proof:

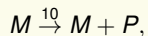
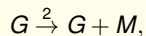
Key observation of proof:

$$X^{\theta+\epsilon}(t) - X^\theta(t) = M^{\theta,\epsilon}(t) + \int_0^t F^{\theta+\epsilon}(X^{\theta+\epsilon}(s)) - F^\theta(X^\theta(s)) ds,$$

where “most” of the jumps have vanished.

Now work on Martingale and absolutely continuous part.

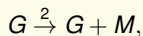
Example: gene transcription and translation



Want

$$\frac{\partial}{\partial \theta} \mathbb{E} \left[X_{\text{protein}}^{\theta}(30) \right], \quad \theta \approx 1/4.$$

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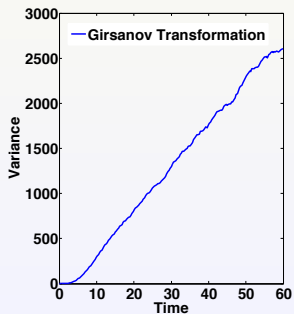
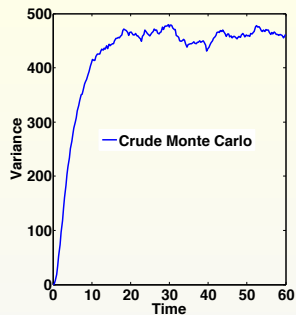
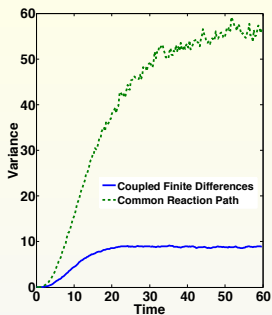
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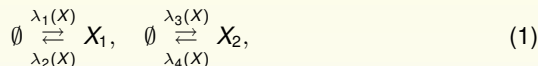
Method	R	95% CI	# updates	CPU Time
Likelihood	689,600	-312.1 ± 6.0	2.9×10^9	3,506.6 S
CMC	246,000	-319.3 ± 6.0	2.1×10^9	2,364.8 S
CRP/CRN	25,980	-316.7 ± 6.0	2.2×10^8	270.9 S
CFD	4,580	-319.9 ± 6.0	2.0×10^7	29.2 S

Table: Each finite difference method used $\epsilon = 1/40$. The exact value is $J(1/4) = -318.073$.

Comparison from 5,000 samples each with $\epsilon = 1/40$



Example: genetic toggle switch



with intensity functions

$$\lambda_1(X(t)) = \frac{\alpha_1}{1 + X_2(t)^\beta}, \quad \lambda_2(X(t)) = X_1(t)$$

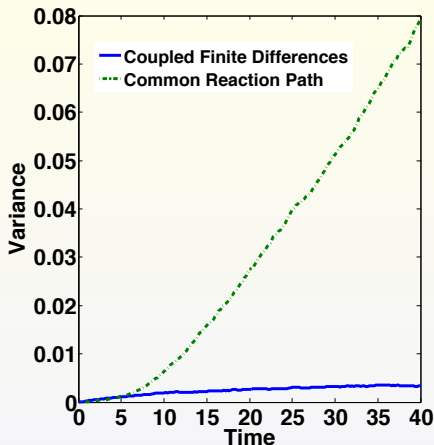
$$\lambda_3(X(t)) = \frac{\alpha_2}{1 + X_1(t)^\gamma}, \quad \lambda_4(X(t)) = X_2(t),$$

and parameter choice

$$\alpha_1 = 50, \quad \alpha_2 = 16, \quad \beta = 2.5, \quad \gamma = 1.$$

- ▶ Begin the process with initial condition $[0, 0]$ and
- ▶ consider the sensitivity of X_1 as a function of α_1 .

Example: genetic toggle switch



(a) Variance to time $T = 40$

Figure: Time plot of the variance of the Coupled Finite Difference estimator versus the Common Reaction Path estimator for the model (1). Each plot was generated using 10,000 sample paths. A perturbation of $\epsilon = 1/10$ was used.

Are these representations only good for simulation? – LLN and ODEs.

Tom Kurtz ~ 1970's

Suppose $X_N(t) = O(N)$. Denote concentrations via

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becomes

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use that

$$\lim_{N \rightarrow \infty} \sup_{\{u \leq U\}} |N^{-1} Y(Nu) - u| = 0,$$

find $\bar{X}_N(t)$ converges to solution of classical ODE

$$x(t) = x(0) + \sum_k \int_0^t \bar{\lambda}_k(x(s)) ds \cdot \xi_k \equiv x(0) + \int_0^t F(x(s)) ds.$$

Diffusions? Argument due to Tom Kurtz

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$$\frac{1}{\sqrt{N}} (Y_k(Nu) - Nu) \approx W_k(u)$$

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use that

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find $\bar{X}_N(t)$ well approximated by chemical Langevin process

$$X(t) = X(0) + \sum_k \zeta_k \int_0^t \lambda_k(X(s)) ds + \frac{1}{\sqrt{N}} \sum_k \int_0^t \sqrt{\lambda_k(X(s))} dW_k(s).$$

or

$$dX(t) = F(X(t))dt + N^{-1/2} \sum_k \zeta_k \sqrt{\lambda_k(X(t))} dW_k(t).$$

Central limit theorem - Kurtz/ Van Kampen

Suppose $X_N(t) = O(N)$. Denote concentrations via

$$\bar{X}_N(t) = N^{-1} X_N(t) = O(1), \quad x(t) = \text{ODE solution.}$$

Let

$$U_N(t) = \sqrt{N} \left(\bar{X}_N(t) - x(t) \right) = \frac{X_n(t) - Nx(t)}{\sqrt{N}}.$$

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$$U_N(t) = \sqrt{N} \left(\bar{X}_N(t) - x(t) \right) = \frac{X_n(t) - Nx(t)}{\sqrt{N}}.$$

Then,

$$\begin{aligned} U_N(t) &= \sqrt{N} \left(N^{-1} \sum_k \zeta_k \tilde{Y}_k \left(N \int_0^t \bar{\lambda}_k(\bar{X}_n(s)) ds \right) \right) \\ &\quad + \sqrt{N} \int_0^t (F(\bar{X}_n(s)) - F(x(s))) ds \\ &\approx \frac{1}{\sqrt{N}} \sum_k \zeta_k \tilde{Y}_k \left(N \int_0^t \bar{\lambda}_k(\bar{X}_n(s)) ds \right) + \int_0^t DF(x(s)) U_n(s) ds. \end{aligned}$$

Central limit theorem - Kurtz/ Van Kampen

Suppose $X_N(t) = O(N)$. Denote concentrations via

$$\bar{X}_N(t) = N^{-1} X_N(t) = O(1), \quad x(t) = \text{ODE solution.}$$

Let

$$U_N(t) = \sqrt{N} \left(\bar{X}_N(t) - x(t) \right) = \frac{X_N(t) - Nx(t)}{\sqrt{N}}.$$

Then,

$$\begin{aligned} U_N(t) &= \sqrt{N} \left(N^{-1} \sum_k \zeta_k \tilde{Y}_k \left(N \int_0^t \bar{\lambda}_k(\bar{X}_n(s)) ds \right) \right) \\ &\quad + \sqrt{N} \int_0^t (F(\bar{X}_n(s)) - F(x(s))) ds \\ &\approx \frac{1}{\sqrt{N}} \sum_k \zeta_k \tilde{Y}_k \left(N \int_0^t \bar{\lambda}_k(\bar{X}_n(s)) ds \right) + \int_0^t DF(x(s)) U_n(s) ds. \end{aligned}$$

use martingale central limit theorem to show that

$$\frac{1}{\sqrt{N}} \tilde{Y}_k(N \cdot) \Rightarrow W_k(\cdot),$$

get $U_n \Rightarrow U$,

$$U(t) = \sum_k \zeta_k W_k \left(\int_0^t \bar{\lambda}_k(x(s)) ds \right) + \int_0^t DF(x(s)) U(s) ds$$

Thanks!

References:

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